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$\theta_1 = 1 \dots (\theta_1 + 8 \dots)$   $\theta_2 = 1 \dots (\theta_2 + 6 \dots)$   $\theta_3 = 1 \dots (\theta_3 + 9 \dots)$  Substitute the  $\theta$  expressions into the heat balance equations. The interior temperatures are the unknowns.

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### CHAPTER 5 INTRODUCTION TO SYSTEMS AND FREQUENCY RESPONSE

ME 482/582 Chapter 5 HW November 7, 2011 Chapter 5 HW Solution Problem 5.1. If you take the Jacobian in frame  $f_0$  from (5.67), then set its determinant to zero, you will obtain the same singular positions as in frame  $f_3$ . This must be true because singularities are a fundamental property of the mechanism. Problem 5.3.

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5.1. We plot the solution to the two equations independently. Since there are two variables in each equation, there are an infinite number of solutions for the equations treated independently. The solution to the system of nonlinear algebraic equations corresponds to ordered pairs of  $(x_1, x_2)$  that satisfy both equations.

## Chapter 5. Solution of a System of Nonlinear Algebraic

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